Problem Solving and Reasoning

Rule-Based System (Production System)



C_i: condition

A_i: Action

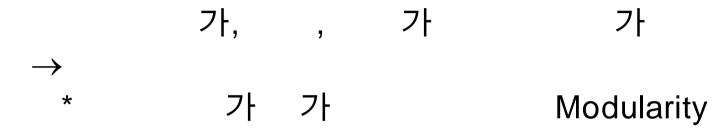
R_i: rule or production

 Loop continues until working patterns no longer matches the condition of any rules

PS

```
rule base (production memory, long term memory)
working memory (shorter term memory)
interpreter (controller)
rule >
If condition 1, then action 1
If condition 1, then action 1
...
rule working memory
```

- PS
 - 1. Separation of knowledge & control
 - 2. Modularity

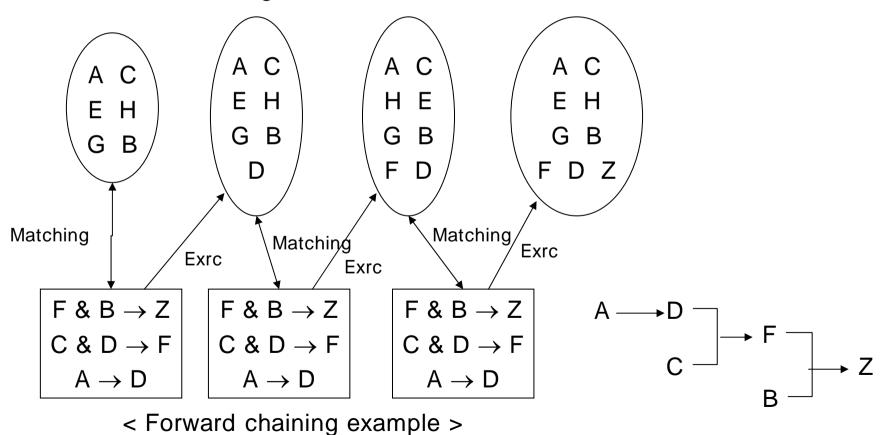


- 3. Uniformity
- 4. Naturalness

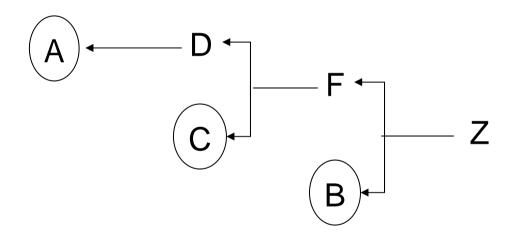
```
( ) . " situation . 가'
```

PS

- -forward chaining
- -backward chaining



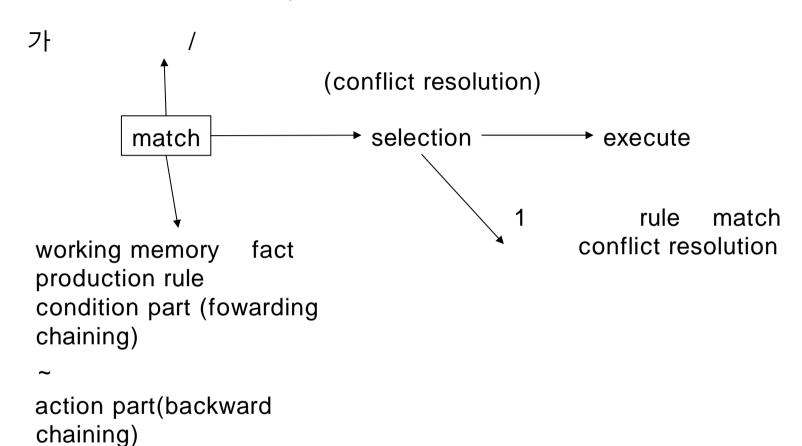
- If problem is to see "Z" is true or not,
 ← Backward chaining is better.
- Z가 Z . ← more efficient!



? Backward chaining vs. Abduction

- Backward chaining abduction
 - backward chaining A→B B가 true , A가 true 가 (A →B & A) →B
 - abduction : (A \rightarrow B & B) \rightarrow A
- Working memory size가 memory
 - > MYCIN context tree prospector semantic net
 - production rule grouping

< Production system >



Conflict Resolution

```
_ 가
```

- Specify ordering : 가
- Rule ordering : rule base
- Data ordering : priority
- Recency ordering : 가 가
- Context limiting : grouping

(rule)

(ex)
production rule :

ba → ab
ca → ac
cb → bc

iteration	WM	conflict set	rule fired
0	c <u>ba</u> ca	1,2,3	1
1	<u>ca</u> bca	2	2
2	acb <u>ca</u>	3,2	2
3	ac <u>ba</u> c	1,3	1
4	a <u>ca</u> bc	2	2
5	aa <u>cb</u> c	3	3
6	aabcc	0	stop

 $\begin{array}{l} \mathsf{Matching} \to \mathsf{Conflict} \; \mathsf{Resolution} \to \mathsf{execution} \\ \mathsf{(interpreter)} \end{array}$

Matching complexity

- working memory : w elements
- production rules : r
- # of elements in condition part : n
- # of cycles for solving problem : c
- total # of match (unification) = wrnc

more likely fail first

Rule 1: if Rule 2: if

the engine is getting gas, and the engine will turn over, then the problem is spark plugs.

and
the lights do not come
then
the problem is battery

the engine does not tu

Rule 3: if Rule 4: if

the engine does not turn over, there is gas in the fue and and the lights do come on there is gas in the care then the problem is the starter motor. the engine is getting the starter motor.

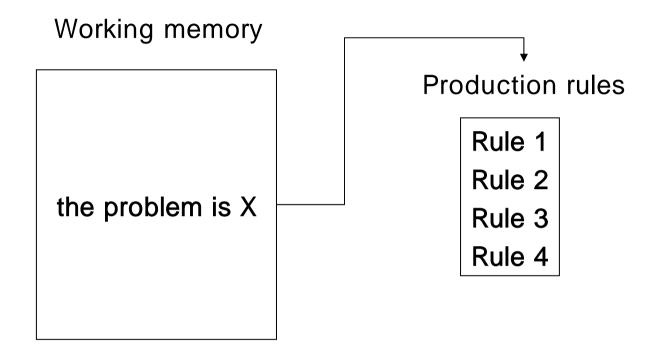
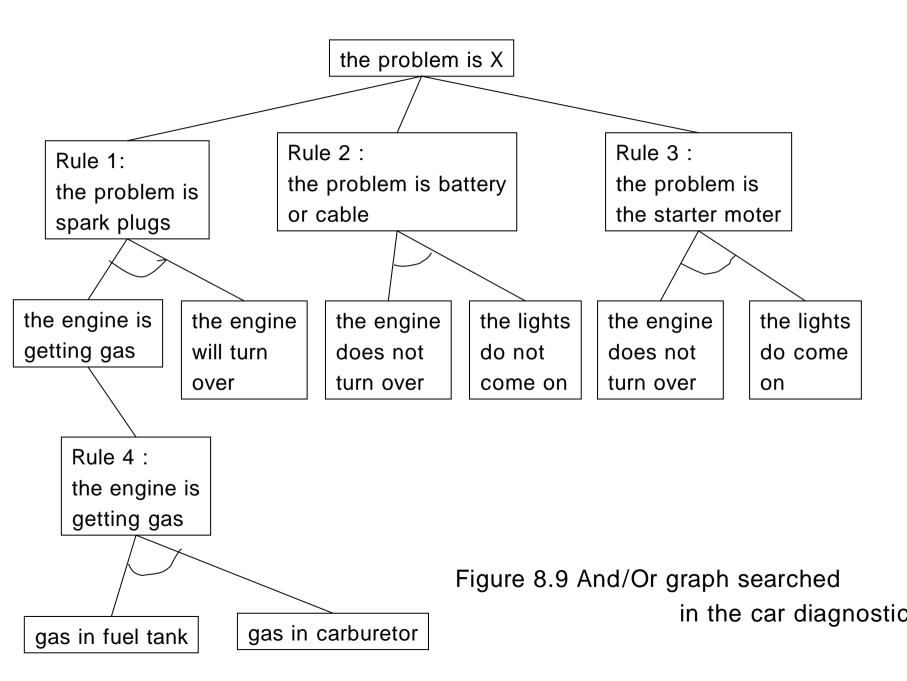


Figure 8.6 The production system at the start of a consultation in the car diagnostic example.



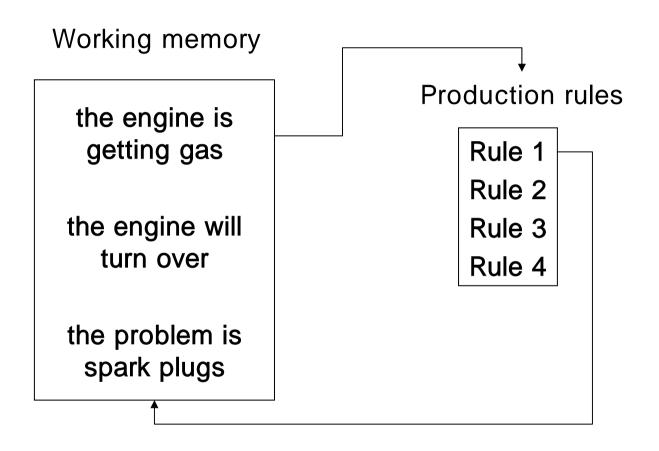


Figure 8.7 The production system after Rule 1 has fired.

Working memory

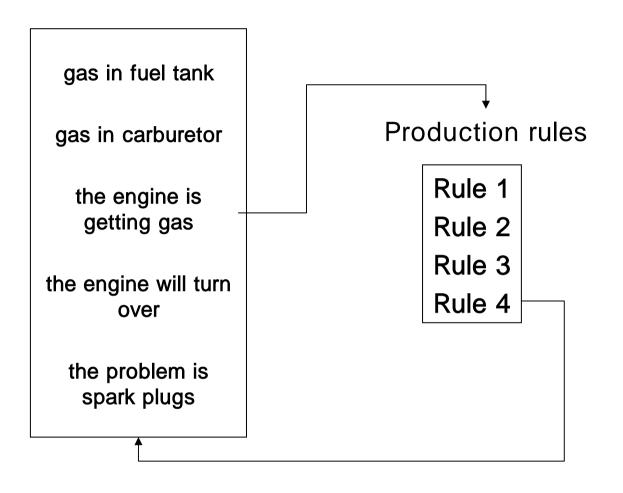


Figure 8.8 The production system after Rule 4 has fired.

(ex) "IDENTIFIER" 7

(Cheetah, tiger, giraffe, zebra, ostrich, penguin, albatross)

R1 : If animal has <u>hair</u> then it is a <u>mammal</u>

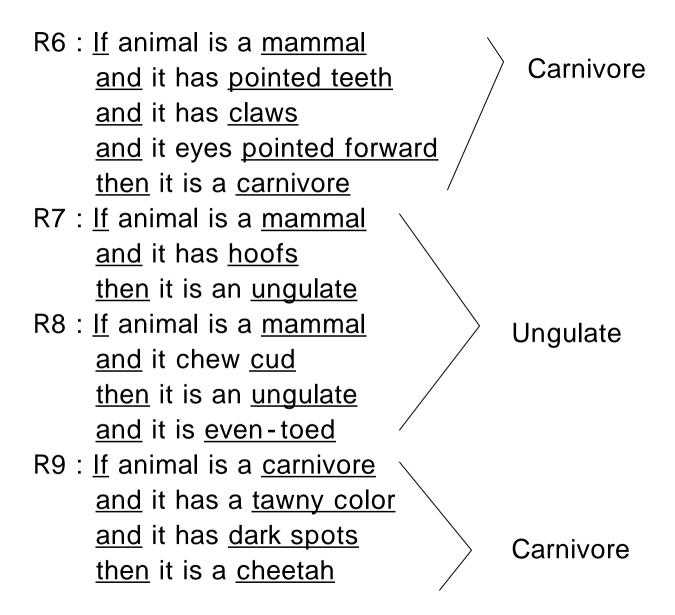
R2 : <u>If animal gives milk</u> then it is a <u>mammal</u>

R3 : <u>If animal has feathers</u> then it is a bird

R4: If animal flies
and it lays egg
then it is a bird

R5 : If animal is a mammal and it eats meat then it is a carnivore

Mammal or bird



R10: If animal is a carnivore
and it has a tawny color
and it has black stripes
then it is a tiger

R11: If animal is an ungulate

and it has long legs

and it has a long neck

and it has a tawny color

and it has dark spots

then it is a giraffe

R12: If animal is an ungulate
and it has a white color
and it has black stripes
then it is a zebra

Ungulate

R13: If animal is a bird

and it does not fly

and it has long legs

and it has a long neck

and it is black and white

then it is an ostrich

R14: If animal is a bird

and it does not fly

and it swims

and it is black and white

then it is a penguin R15: If animal is a bird

and it is a good flyer then it is an albatross

bird

- Now the following has been observed.
 - 1. Tawny color & dark spots. \rightarrow ?R₁₀ ?R₁₁
 - 2. Gives a milk & chews its cud. R₂,R₈
 - 3. long legs & log neck. $\rightarrow R_{11}$ The animal is giraffe.

•

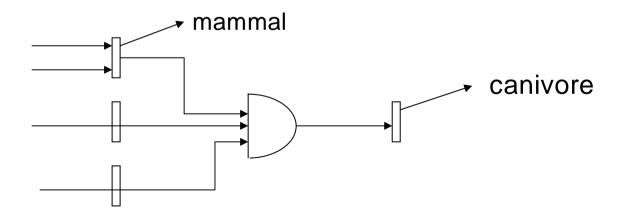
1. 가? (why)

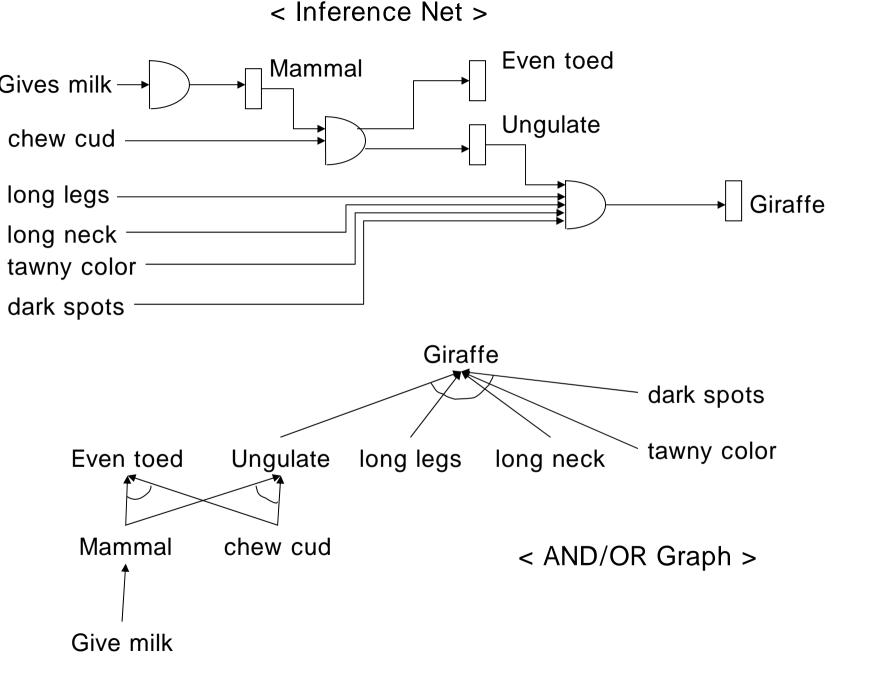
2. 가? (how)

Answer

– for why : forward

- for how: backward





$$P(H_i | E) = \frac{P(E | H_i)P(H_i)}{\sum_{k=1}^{n} (P(E | H_k)P(H_k))}$$

- P(H_i|E): Prob. that H_i true given evidence E
- P(H_i): Prob. that H true overall
- P(E|H_i): Prob. of observing evidence E when H_i true
- n : number of possible hypotheses

$$P(E) = \sum_{k=1}^{n} P(E | H_k) P(H_k)$$

$$P(A \mid B)P(B) = P(A, B)$$

$$P(B \mid A)P(A) = P(B, A)$$

$$\therefore P(A \mid B)P(B) = P(B \mid A)P(A)$$

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$$

Bayes' rule: known fact → unknown fact probability

$$P(X \mid Y)P(Y) = P(Y \mid X)P(X)$$

$$P(X \mid Y) = \frac{P(Y \mid X)}{P(Y)}$$

$$P(X|Y)$$
:

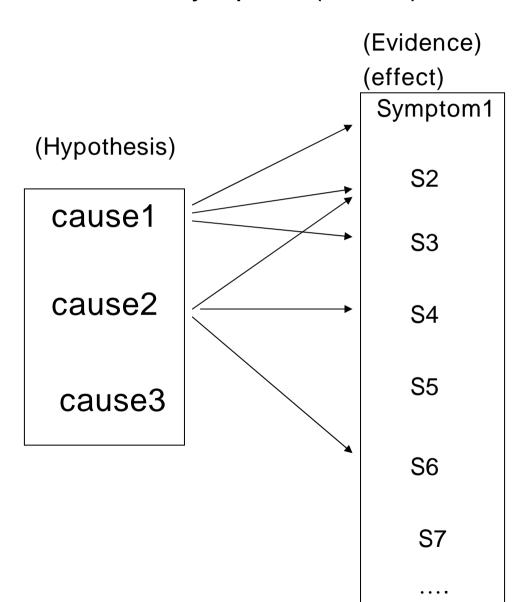
$$P(Y|X)$$
:

$$P(X) = 0.1$$

$$P(Y) = 0.3$$
 $P(Y | X) = 0.9$

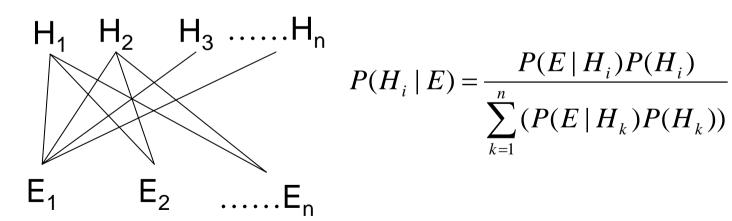
$$P(X \mid Y) = \frac{0.1 \times 0.9}{0.3} = \frac{0.09}{0.30} = \frac{3}{10} = 0.3$$

< Cause - Symptom(effect) relation >



Two major problems of Bayesian

- All relations of evidences are independent.
- Adding new hypotheses and evidences, it is necessary to rebuild probability tables.



$$P(Y | X, Y) = \frac{P(X | Y, E)P(Y | E)}{P(X | E)}$$

$$P(Z \mid X, Y) = \frac{P(X, Y \mid Z)P(Z)}{P(X, Y)} = \frac{P(X \mid Z)P(Y \mid Z)P(Z)}{P(X, Y)}$$
$$= \alpha(P(Z)P(X \mid Z)P(Y \mid Z)$$

If P(X|Z) & P(Y|Z) are independent α : normalization constant

? Symptom2가 cause2

cause1

cause \rightarrow symptom symptom \rightarrow cause

known unknown

rule
$$r_1$$
 Bayes rule
$$P(C_1 | S_2) = \frac{P(S_2 | C_1)P(C_1)}{P(S_2 | C_1)P(C_1) + P(S_2 | C_2)P(C_2)}$$

$$C_1: , C_2: \\ S_1: \\ S_2: \\ P(C_1 | S_1) = \frac{P(S_1 | C_1)P(C_1)}{P(S_1 | C_1)P(C_1) + P(S_1 | C_3)P(C_3)}$$
rule r_3

Certainty Factor

- Bayes' theorem
- in traditional prob. theory the sum of confidence for a relationship and confidence against the same relationship must add to 1.
- But, often the expert may have confidence
 0.7(e.g.) that some relationship is true & have no fealing about its being not true.

Certainty Factor

가? completely completely right wrong 0 completely unknown completely right wrong CF CF CF

• C가 dependent

Input CF

$$\Rightarrow C_1 \times C_2 \times ... \times C_n$$

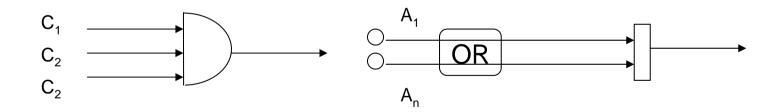
• A가 dependent

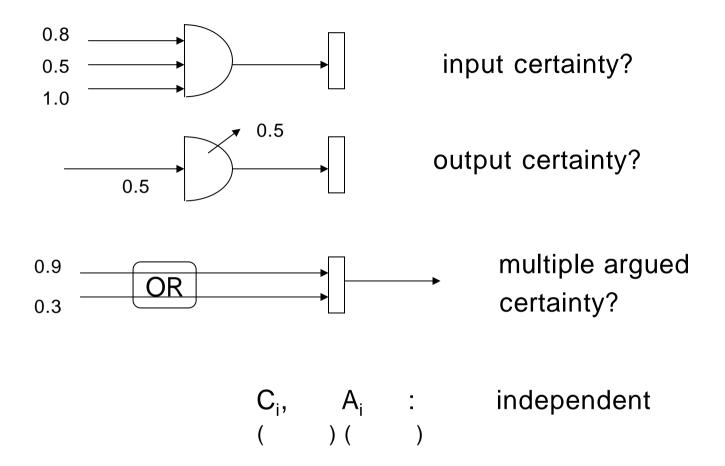
Multiple argued certainty

$$\Rightarrow$$
 R_i=A_i/(1 - A_i); Certainty Ratio

$$\rightarrow R_1 \times R_2 \times ... \times R_n = R$$

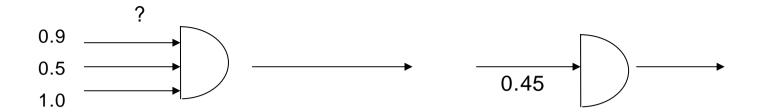
$$\rightarrow$$
 A = R/(1+R)





Multiple argued

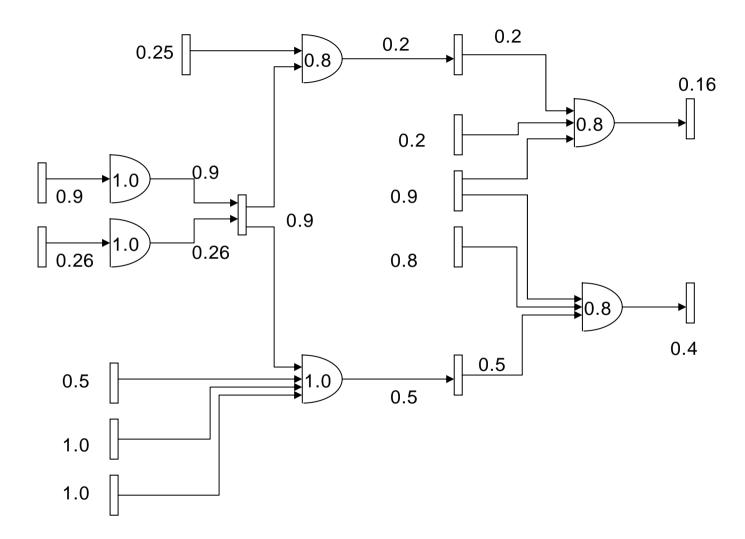
⇒ some conclusion with different rules



CF 0.9 0.25
CR
$$R_1 = \frac{0.9}{1 - 0.9} = 9$$
 $\frac{0.25}{1 - 0.25} = \frac{1}{3} = R_2$

$$R_1 \times R_2 = 9 \times \frac{1}{3} = 3 = R$$

$$C = \frac{R}{1+R} = 0.75$$



Conditional problem

	fever	⊣fever
cold	0.04	0.06
⊸cold	0.01	0.89

$$P(cold) = 0.04 + 0.06 = 0.1$$

$$P(cold \lor fever) = 0.04 + 0.01 + 0.06 = 0.11$$

$$= P(cold) + P(fever) - P(cold \land fever)$$

$$P(cold \mid fever) = \frac{P(fever \land cold)}{P(fever)}$$

$$= \frac{0.04}{0.04 + 0.01} = 0.8$$

Dempster-Shaper theory

- deal with the distinction between uncertainty & ignorance
- computes the probability that the evidence supports the proposition rather than computing the probability of a proposition
 - → Belief function
- e.g. Coin flipping
 - Head가 belief
 - (1) since we don't know coin is fair or not Bel(Head) = 0 Bel(¬Head) = 0
 - (2) 가가 fair certainty가 90% Bel(Head) = 0.9 x 0.5 = 0.45

$$Bel(\neg Head) = 0.9 \times 0.5 = 0.45$$

Dempster-Shaper theory(cont'd)

```
(3) \sim 100\%
            Bel(Head) = 1 \times 0.5 = 0.5
            Bel(\neg Head) = 1 \times 0.5 = 0.5
Plausibility = 1 - Bel()
(1) : Bel(Head) = 0, Plausibility = 1 - Bel(Head) = 1
< Probability interval >
(1) [0, 1]
(2) [0.45, 0.55]
(3) [0.5, 0.5]
```

Dempster-Shaper Theorem

- Belief
 - $-b(\phi)=0$
 - $-b(\theta)=1$
 - for all $A \subset \theta$, $0 \le b(A) \le 1$
- Support

$$spt(D_j) = \sum_{D_r \subset D_j} b(D_r)$$

- Plausibility
 - $pI(D_j) = 1 spt(\neg D_j)$

Example 0

		Coin A		
		front(0.8)	back(0.2)	
Coin B	front(0.6)	0.48	0.12	
	back(0.4)	0.32	0.08	

```
Belief(Coin A(front) and Coin B(front)) = 0.48
```

Belief(Coin A(front) and Coin B(back)) = 0.32

Belief(Coin A(back) and Coin B(front)) = 0.12

Belief(Coin A(back) and Coin B(back)) = 0.08

```
Support(same) = Belief(Coin A(front) and Coin B(front)) +
    Belief(Coin A(back) and Coin B(back)) = 0.56
Plausibility(same) = 1 - Belief(Coin A(front) and Coin B(back))
    - Belief(Coin A(back) and Coin B(front)) = 0.56
```

Example 1

		Melissa		
_		broken(0.9)	don't know(0.1)	
Bill	not broken(0.8)	0	(not broken) 0.08	
	don't know(0.2)	(broken) 0.18	(don't know) 0.02	

Belief(broken and not broken) = 0

Belief(broken) = 0.18/0.28 = 0.643

Belief(not broken) = 0.08/0.28 = 0.286

Belief(don't know) = 0.02/0.28 = 0.071

Support(broken) = Belief (broken = 0.643 Plausibility(broken) = 1 - Belief(not broken) = 0.714

Support(not broken) = Belief(not broken) = 0.286 Plausibility(not broken) = 1 - Belief(broken) = 0.357

Resolution Theorem Proving (Refutation)

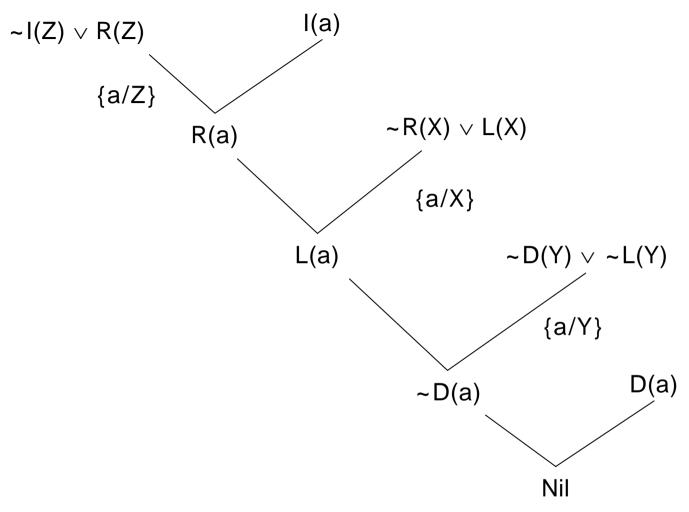
Steps

- 1. Put the premises into clause form
- 2. Add the negation of what is to be proved in clause form to the set of premises.
- 3. Resolve these clauses together, producing new clauses that logically follows.
- 4. Produce a contradiction by generating the empty clause.

Resolution example

- 1. Whoever can read is literate.
- 2. Dolphines are not literate.
- 3. Some dolphines are intelligent cannot read?
- → Some who are intelligent cannot read?
- 1. $(\forall X)[R(X) \Rightarrow L(X)]$
- 2. $(\forall X)[D(X) \Rightarrow \neg L(X)]$
- 3. $(\exists X)[D(X) \land I(X)]$
- 4. $(\exists X)[I(X) \land \neg R(X)]$
- 1; $\neg R(X) \lor L(X)$
- 2; $\neg D(Y) \lor \neg L(Y)$
- 3; $D(a) \wedge I(a)$
- $\neg 4$; $\neg I(Z) \lor R(Z)$

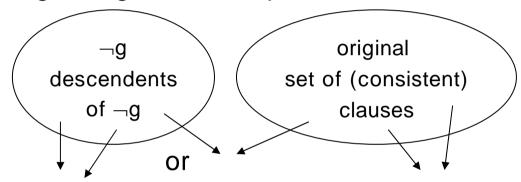
$$\neg \exists X [\sim] = \forall X \neg [\sim]$$



5 : resolution example

therefore $I(a) \wedge \neg R(a)$

- Breadth First Strategy: complete
- Set of support strategy
 - at least one of the resolvents is either the negated goal clause or a clause produced by resolutions on the negated goal → complete



- Unit Preference strategy: complete
 - <u>Unit resolution</u>: not complete

 one of the resolvents always be a unit clause.
- Linear Input Form Strategy: not complete

- Once the theorem prover shows that the negated goal is inconsistent with the given set of axioms, it follows that the original goal must be consistent → proof of the theorem
- Resolution is a sound inference rule
 - (P∨Q) ∧ (¬G∨R) → P∨R
 P∨R logically follows from (P∨Q) ∧ (¬G∨R)
 ∴ sound
 - But it is not complete.
 - i.e. given set of axiom

logically follow

fact

- refutation complete.

i.e. the empty or null clause can always be generated wherever a contradiction in the set of clauses exists.

- Refutation
 - inference procedure using resolution, proof by contradiction

Refutation

- proof by contradiction
- To prove P, assume P is false & prove a contradiction
- (S ∧ ¬P \Rightarrow false) \Leftrightarrow (S \rightarrow P)

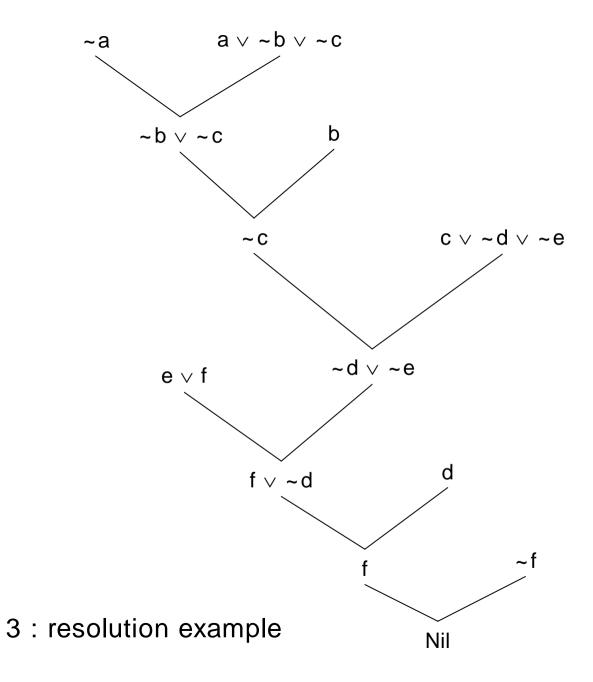
resolution example

given,

- 1. $b \land c \Rightarrow a$ 2. b3. $d \land e \Rightarrow c$ 4. $e \lor f$ 5. $d \land \neg f$

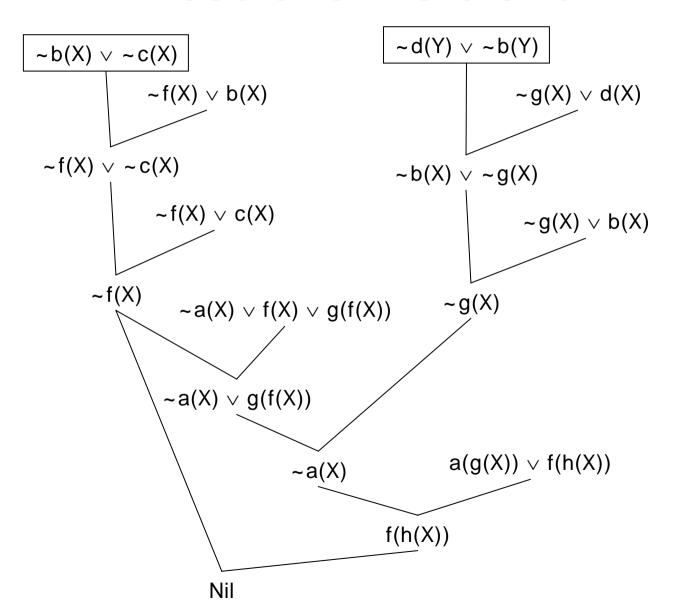
clause form

- /1. \neg (b \wedge c) \vee a \Rightarrow \neg b \vee \neg c \vee a 2. b 3. \neg (d \wedge e) \vee c \Rightarrow \neg d \vee \neg e \vee c
- 4. $e \vee f$



```
- < Axioms >
   \neg a(X) \lor f(X) \lor g(f(X))
   \neg f(X) \lor b(X)
   \neg f(X) \lor c(X)
   \neg g(X) \lor b(X)
   \neg g(X) \lor d(X)
   a(g(X)) \vee f(h(X))
- < goal >
   (\exists X)(\exists Y)\{[b(X) \land c(X)] \lor [d(Y) \land b(Y)]\}
- < ¬goal >
    \neg b(X) \lor \neg c(X)
    \neg b(Y) \vee \neg d(Y)
```

Resolution refutation

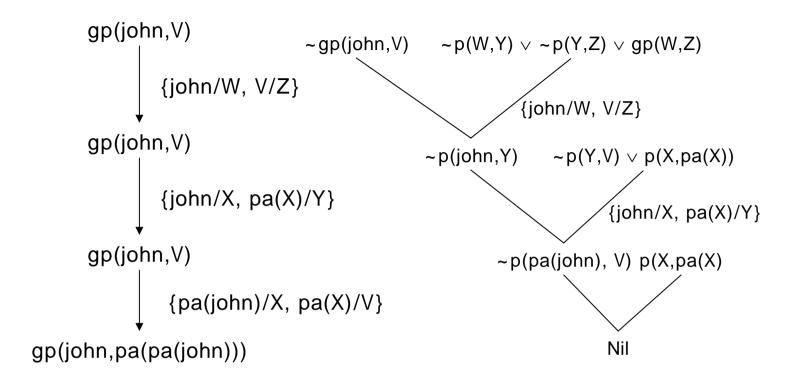


example problem

- Everyone has a parent.
 - 1. $(\forall X)(\exists Y)p(X,Y)$
- A parent of a parent is a grandparent.
 - 2. $(\forall X)(\forall Y)(\forall Z)p(X,Y) \land p(Y,Z) \Rightarrow gp(X,Z)$
- goal; John has a grandparent?(∃W)(gp(john,W))
- negation of goal3. ¬gp(john,W)

Clause form

- p(X,pa(X))
- 2. $\neg p(W,Y) \vee \neg p(Y,Z) \vee gp(W,Z)$
- 3. $\neg gp(john, V)$



 $V \rightarrow pa(X) \rightarrow pa(pa(john))$

* gp(john, pa(pa(john))) is proved

tautology proof & answer extraction

goal statement negation tautology
 e.g.) ¬gp(john,V) → ¬gp(john,V) ∨ gp(john,V)

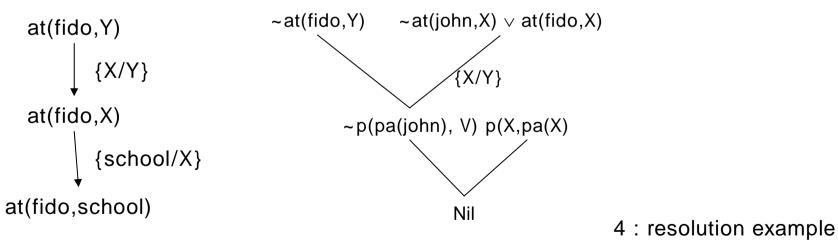
Resolution

- ?tolology
 - $p(X) \vee \neg p(X)$
- subsume clause
 - p(john) subsumes ∀X p(X)
 - p(X) subsumes $p(X) \vee q(X)$
- procedure attachment

Τ	F evaluate	literal	evaluate	
_	٦L	literal T	evaluate	
_	가	literal F	evaluate	literal

"If Fido goes where John goes & if John is at school, where is Fido?"

- 1. $(\forall X)[at(john,X) \Rightarrow at(fido,X)]$
- 2. at(john,school)
- 3. $(\exists X)$ at(fido, X)? \rightarrow goal
- 1; \neg at(john,X) \lor at(fido,X)
- 2; at(john,school)
- $\neg 3$; $\neg at(fido,X)$



•retain original goal & apply all the substitutions of the refutation to this clause.

we find the answer.

therefore at(fido,school) fido school .

- Anyone passing his history exams and winning the lottery is happy
 - $\forall X(pass(X, history) \land win(X, lottery) \rightarrow happy(X))$
- Anyone who studies or is lucky can pass all his exams

```
\forall X \forall Y (studies(X) \lor lucky(X) \rightarrow pass(X,Y))
```

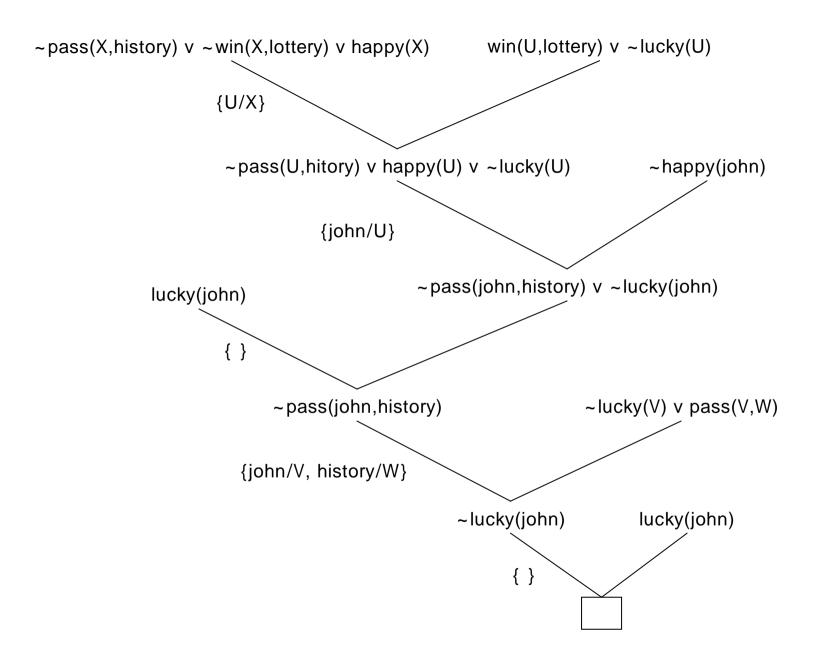
- John did not study but he is lucky
 - ¬study(john) ∧ lucky(john)
- Anyone who is lucky wins the lottery

```
\forall X(lucky(X) \rightarrow win(X, lottery))
```

then

 Is John happy? happy(john)

- < Clause form >
- ¬pass(X,history) ∨ ¬win(X,lottery) ∨ happy(X)
- 2. ¬study(Y) ∨ pass(Y,Z)¬lucky(W) ∨ pass(W,V)
- ∃study(john)
 lucky(john)
- 4. \neg lucky(U) \lor win(U,lottery)
- 5. ¬happy(john)?



Resolution strategy

1. Breadth-First strategy

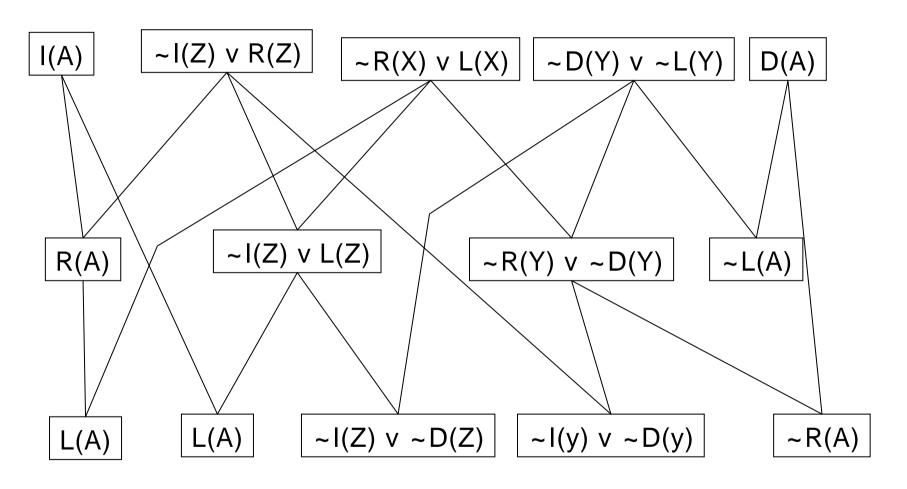
N clause in the original clause set.

1st level: N² ways of combination

2nd level: Resolve the clauses produced at the 1st level with all the original clauses.

nth level: Resolve all clauses at the level n-1 against the elements of the original clause set & all causes previously produced.

- * large search space
- * find the shortest path solution
- * if refutation exist, if always finds. \rightarrow complete.



< Breadth - First strategy >

1. The set of support strategy

Suppose a set of input clauses : S subset of S that includes the negation of the goal : T

S is contradictory ↔ T is contradictory

- * The negation of what we want to prove true is responsible for causing the clause space to be contradictory
- * Resolution parent <u>goal</u> descendent .

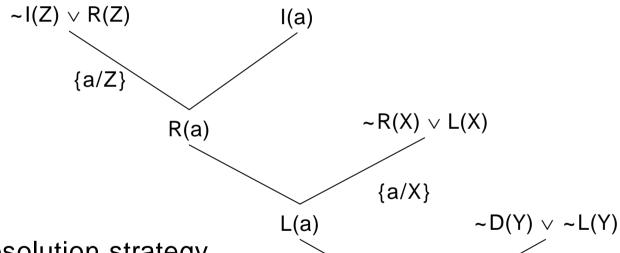
$$\sim I(Z) \vee R(Z) \quad I(A) \quad \sim R(X) \vee L(X) \sim D(Y) \vee \sim L(Y)$$

R(A) ~I(Z) v L(Z)

L(A)

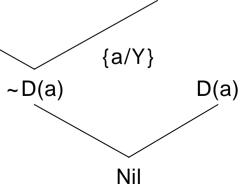
 $\sim D(A)$ $\sim I(A)$ $\sim D(A)$

- Unit Preference strategy(
 - literal 가 clause resolution 가 .
 - \rightarrow Resolution literal
 - → complete



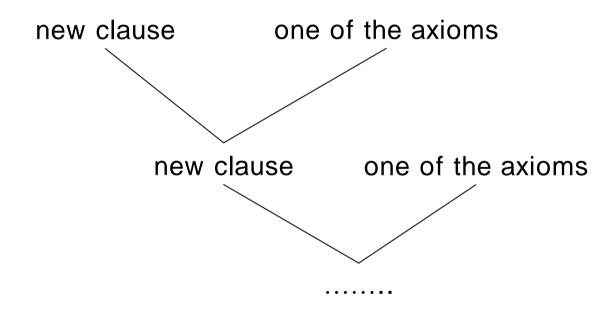
Unit resolution strategy

→ not complete



Nil

- Linear Input Form strategy
 - negated goal & the original axioms
 - take the negated goal & resolve it with one of the axioms.



- •No previously derived clause is used.
- •No two axioms are used.
- not complete